

# **Data Sheet**

# **R-Series RT4 SSI**

Magnetostrictive Linear Position Sensors

- Redundant SSI output
- High temperature rod
- IP68 ingress protection



#### MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

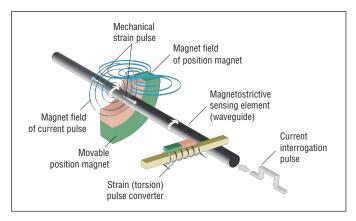


Fig. 1: Time-based magnetostrictive position sensing principle

#### **RT4 SENSOR**

Robust, non-contact and wear-free, the Temposonics® linear position sensors provide best durability and accurate position measurement solutions in harsh industrial environments. Designed for demanding applications that require redundancy and detached electronics due to high temperature or high reliability requirements. The position measurement accuracy is tightly controlled by the quality of the waveguide which is manufactured by Temposonics. The position magnet is mounted on the moving machine part and travels contactlessly over the sensor rod with the built-in waveguide.

Redundant R-series detached electronics for enhanced safety applications

#### RT41 (ste hastonp speetcifectation (ns) to +100 °C)

- Detached electronics up to 600 mm from sensor rod
- IP68 ingress protection
- Linear, absolute measurement
- Non-contact sensing technology
- Linearity deviation less than 0.02 %
- Direct 24/25/26 bit SSI output, gray/binary formats
- LEDs for sensor status and diagnostics

#### Applications:

- Steel, wood, power generation, fluid power



Fig. 2: Typical application: metal processing

## **TECHNICAL DATA**

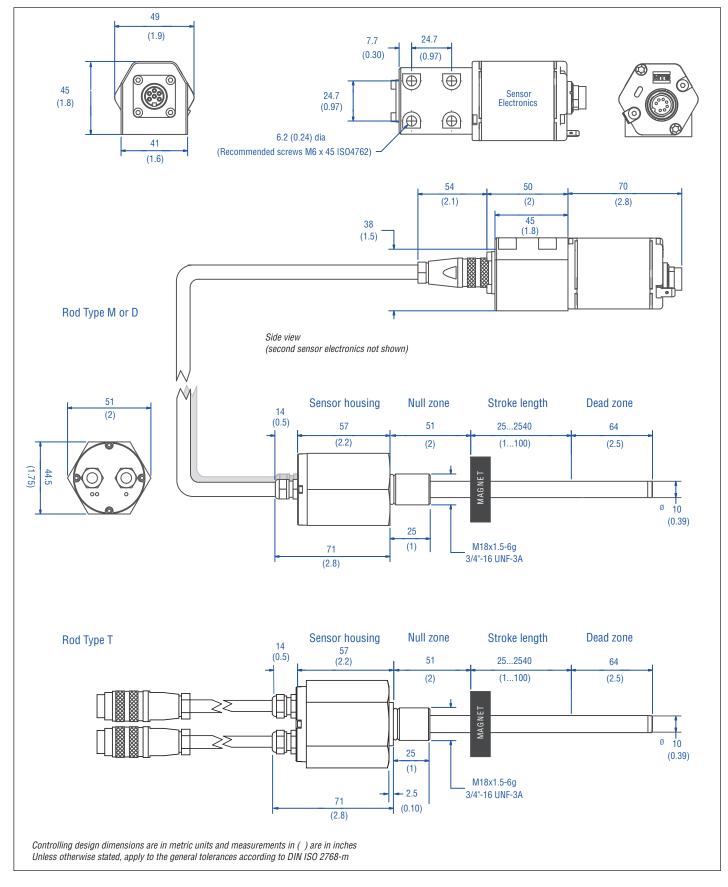
Output			
Interface	SSI (Synchronous Serial Interface) - differential signal in SSI standard (RS 422)		
Data protocol	Binary or Gray, optional: parity and error bit		
Data length	24, 25, or 26 bit		
Data transmission rate	70 kBaud*1 MBaud, depending on cable length:  Length		
Measured value	Position		
Measurement parameters			
Resolution	1 μm, 2 μm, 5 μm, 10 μm, 20 μm, 50 μm, 100 μm		
Cycle times	Stroke length         300         750         1000         2000 mm           Measurement rate         3.7         3.0         2.3         1.2 kHz		
Linearity <sup>1</sup>	< ±0.02 % F.S. (minimum ±50 μm)		
Repeatability	0.001 % F.S. (minimum ±2.5 μm)		
Operating conditions			
Operating temperature	Sensor electronics: -40 °C (-40 °F) to +75 °C (+167 °F)  Sensor rod with interconnection cable: -40 °C (-40 °F) to +100 °C (+212 °F)		
Humidity	90% humidity, no condensation		
Ingress protection	Sensor electronics: IP67 (with professionally mounted housing and connectors) Sensor housing with interconnection cable: IP68		
Shock test	100 g (single hit) / IEC standard 60068-2-27		
Vibration test	10 g / 10 to 2000 Hz, IEC standard 60068-2-6 (resonance frequencies excluded)		
EMC test <sup>2</sup>	Electromagnetic emission: IEC/EN 50081-1 Electromagnetic susceptibility: IEC/EN 50082-2 IEC/EN 61000-4-2/3/4/6, level 3/4 criterium A		
Magnet movement velocity <sup>1</sup>	Any		
Design/Material			
Sensor electronics	Aluminum housing with diagnostic LED display. (LEDs located beside connector/cable exit)		
Sensor housing	Stainless steel 1.4305, AISI 304L		
Stroke length	252540 mm (1100 in.)		
Operating pressure	350 bar static, 690 bar peak (5000 psi, 10,000 psi peak)		
Mechanical mounting			
Mounting position	Any orientation		
Mounting instruction	Please consult the technical drawings		
Electrical connection			
Connection type	7 pin connector M16 or integral cable		
Operating voltage	+24 VDC (-15% / +20 %)		
Ripple	≤ 0.28 Vpp		
Current consumption	100 mA per sensor electronics		
Dielectric strength	500 VDC (DC ground to machine ground)		
Polarity protection	up to -30 VDC		
Overvoltage protection	up to 36 VDC		

 $<sup>^{*}\!\!/</sup>$  with standard monoflop of 16  $\mu s$ 

<sup>1/</sup> With position magnet # 201 542-2

<sup>2/</sup> Sensor rod and interconnection cable are mounted in a metal housing (e.g. in a cylinder).

## **TECHNICAL DRAWINGS (Detached electronics with side cable entry)**



#### **CONNECTOR WIRING**

#### M16 connector

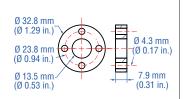
D70	Pin	Function
0000	1	Data (–)
	2	Data (+)
	3	Clock (+)
	4	Clock (-)
	5	+24 VDC (-15 / +20 %)
	6	DC Ground (0 V)
	7	n.c.

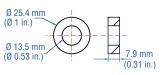
#### Cable outlet

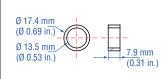
Cable	Function
GY	Data (-)
PK	Data (+)
YE	Clock (+)
GN	Clock (-)
BN	+24 VDC (-15 / +20 %)
WH	DC Ground (0 V)

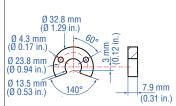
### FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Catalog 3550929

### **Position magnets**









# Standard ring magnet 0032.8 Part no. 201 542-2

Material: PA ferrite GF20
Weight: ca. 14 g
Operating temperature:
-40...+105 °C (-40...+221 °F)
Surface pressure: max. 40 N/mm²
Fastening torque for M4 screws:
max. 1 Nm

#### Ring magnet OD25.4 Part no. 400 533

Material: PA ferrite Weight: ca. 10 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 40 N/mm²

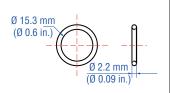
#### Ring magnet 0D17.4 Part no. 401 032

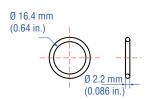
Material: PA neobind Weight: ca. 5 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 20 N/mm²

#### U-magnet 0D33 Part no. 251 416-2

Material: PA ferrite GF20 Weight: ca. 11 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 40 N/mm² Fastening torque for M4 screws: max. 1 Nm

#### **Optional installation hardware**





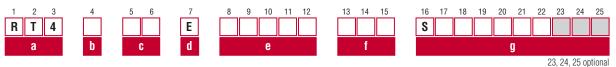
#### 0-ring Part no. 401 133

Material: Fluoroelastomer 75 ± 5 durometer Application: M-style housings

#### 0-ring Part no. 560 315

Material: Fluoroelastomer 75 ± 5 durometer Application: T and D -style housings

#### **ORDER CODE**



**Output (continued)** Sensor model S(17)(18)(19)(20)(21)(22)(23)(24)(25) = Synchronous Serial InterfaceT 4 Rod version Sensor rod style Format (box no. 18) M Flat faced Metric threaded flange, M18x1.5 В Binary G Flat faced US customary threaded flange, 3/4"-16 Gray Raised face US customary threaded flange, 3/4"-16 Resolution (box no. 19) 0.005 mm Sensor rod interconnection cable 2 0.01 mm **B** 1 250 mm (9.8 in.) Santoprene cable, hanging connector 3 0.05 mm 2 400 mm (15.7 in.) Santoprene cable, hanging connector 4 0.1 mm 3 600 mm (23.6 in.) Santoprene cable, hanging connector 5 0.02 mm 6 0.002 mm **Electronics housing style** 0.001 mm 8 Side cable electronics connection Filtering performance (box no. 20) Noise reduction filter (8 values) Stroke length G Noise reduction filter (8 values) + error delay 10 cycles for mm (0025...2540 mm in 5 mm increments)  $X \parallel X \parallel X \parallel$ Signal options (box no. 21 and 22)  $X \mid X \mid X$ U for inches (001.0...100.0 in. in 0.1 in. increments) 0 Measuring direction forward 0 Measuring direction reverse **Connection type** 0 Measuring direction forward, synchronized measurement Integral connector 0 Measuring direction forward, Bit 25 = Alarm, **D 7 0** 7pin M16 connector Bit 26 = Parity even Integral Cables (box No. 13, 14, 15) 9 Advanced Signal Options (Use next fields 23, 24, 25) 9 | Integral high-performance cable, orange jacket with Measurement contents (box no. 23) pigtail termination 1 Position R Integral cable, PVC jacket, pigtail termination, standard Direction and Sync mode (box no. 24) Integral cable, black polyurethane jacket with pigtail F Forward async termination 2 Forward sync1 Cable length 5 Reverse async

#### **Operating voltage**

Without selection input voltage, 24 VDC

#### g | Output

S(17)(18)(19)(20)(21)(22)(23)(24)(25) = Synchronous Serial Interface

Encode in feet if using US customary stroke length Encode in meters if using metric stroke length

3 (03) to 98 (98) ft. or 1 (01) to 30 (30) meters.

#### Data length (box no. 17)

- **1** 25 bits
- **2** 24 bits
- **3** 26 bits

#### **DELIVERY**



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Sensor, O-ring

Accessories have to be ordered separately.

Operation manuals & software are available at:

Communication Diagnostics (box no. 25)

Additional alarm bit + parity even bit

www.temposonics.com

Reverse sync1

No further option



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