

## Data Sheet

# R-Series V RP5 POWERLINK

## Magnetostrictive Linear Position Sensors

- Minimum position resolution 0.5  $\mu\text{m}$
- Position and velocity measurements for up to 30 magnets
- Field adjustments and diagnostics using the new TempoLink smart assistant



**V**  
THE NEW GENERATION

## MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

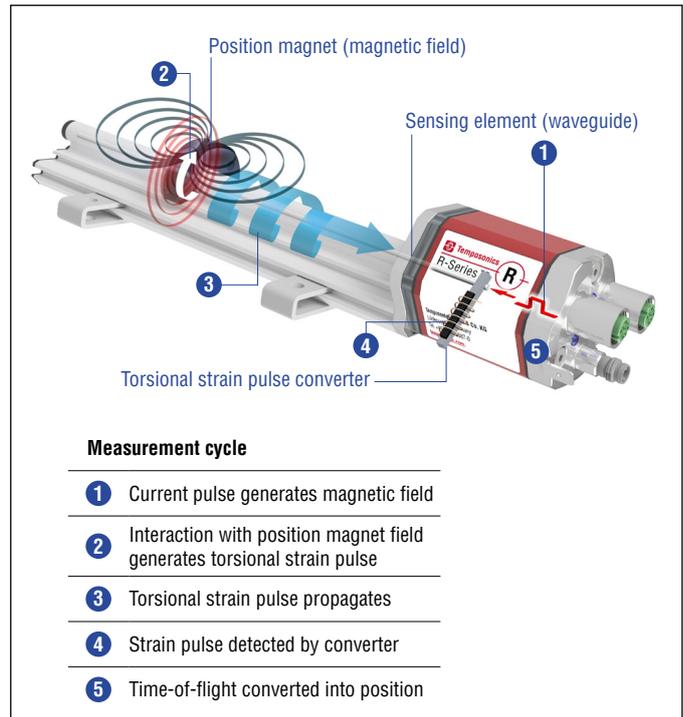


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

## R-SERIES V POWERLINK

Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The R-Series V is the long term solution for harsh environments that have high levels of shock and vibration. The sensor is equipped with POWERLINK V2 and supports a minimum cycle time of 250  $\mu$ s. In time-critical applications, the linear extrapolation can be activated. This offers a cycle time of 200  $\mu$ s for every sensor stroke length. The measurement of the sensor can be synchronized to the polling cycle of the controller. Temposonics® R-Series V sensors are available with internal linearization which offers improved linearity for overall higher accuracy of the position measurement values. In addition to the measured position value via the POWERLINK protocol further data about the current sensor status, such like the total distance travelled, the internal temperature and the total operating hours, can be displayed for diagnostic purposes.

With many outstanding features the R-Series V sensors are fit for a very broad range of applications.

## TempoLink® SMART ASSISTANT

The TempoLink® smart assistant is an accessory for the R-Series V family of sensors that supports setup and diagnostics. Depending on the sensor protocol it enables the adjustment of parameters like measurement direction, resolution and filter settings. For diagnostics and analysis of operational data the R-Series V sensors continuously track values such as total distance traveled by the position magnet, internal temperature of the sensor and the quality of the position signal. This additional information can be read out via TempoLink® smart assistant even while the sensor remains operational in the application. TempoLink® smart assistant is connected to the sensor via the power connection, which now adds bidirectional communication for setup and diagnostics. The TempoLink® smart assistant is operated using a graphical user-interface that will be displayed on your smartphone, tablet, laptop or PC. Just connect your Wi-Fi-enabled device to TempoLink® Wi-Fi access point and go to the website URL for the user-interface.



Fig. 2: R-Series V sensor with TempoLink® smart assistant

## TECHNICAL DATA

Output						
Interface	Ethernet POWERLINK					
Data protocol	POWERLINK V2					
Measured value	Position, velocity/option: Simultaneous multi-position and multi-velocity measurements up to 30 magnets					
Measurement parameters						
Resolution: Position	0.5...100 µm (selectable)					
Cycle time <sup>1</sup>	Stroke length	≤ 50 mm	≤ 715 mm	≤ 2000 mm	≤ 4675 mm	≤ 6350 mm
	Cycle time	250 µs <sup>1</sup>	500 µs	1000 µs	2000 µs	2800 µs
Linearity deviation <sup>2</sup>	Stroke length	≤ 500 mm	> 500 mm			
	Linearity deviation	≤ ±50 µm	< 0.01 % F.S.			
	Optional internal linearization: Linearity tolerance (applies for the first magnet for multi-position measurement)					
	Stroke length	25...300 mm	300...600 mm	600...1200 mm	1200...3000 mm	3000...5000 mm   5000...6350 mm
	typical	± 15 µm	± 20 µm	± 25 µm	± 45 µm	± 85 µm   ± 95 µm
	maximum	± 25 µm	± 30 µm	± 50 µm	± 90 µm	± 150 µm   ± 190 µm
Repeatability	< ±0.001 % F.S. (minimum ±2.5 µm) typical					
Hysteresis	< 4 µm typical					
Temperature coefficient	< 15 ppm/K typical					
Operating conditions						
Operating temperature	-40...+85 °C (-40...+185 °F)					
Humidity	90 % relative humidity, no condensation					
Ingress protection	IP67 (connectors correctly fitted)					
Shock test	150 g/11 ms, IEC standard 60068-2-27					
Vibration test	30 g/10...2000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)					
EMC test	Electromagnetic emission according to EN 61000-6-3					
	Electromagnetic immunity according to EN 61000-6-2					
	The sensor meets the requirements of the EC directives and is marked with <b>CE</b>					
Magnet movement velocity	Magnet slider: Max. 10 m/s; U-magnet: Any; block magnet: Any					
Design / Material						
Sensor electronics housing	Aluminum (painted), zinc die cast					
Sensor profile	Aluminum					
Stroke length	25...6350 mm (1...250 in.)					
Mechanical mounting						
Mounting position	Any					
Mounting instruction	Please consult the technical drawings on <a href="#">page 4</a>					
Electrical connection						
Connection type	2 × M12 female connectors (D-coded), 1 × M8 male connector; 2 × M12 female connectors (D-coded), 1 × M12 male connector (A-coded)					
Operating voltage	+12...30 VDC ±20 % (9.6...36 VDC)					
Power consumption	Less than 4 W typical					
Dielectric strength	500 VDC (DC ground to machine ground)					
Polarity protection	Up to -36 VDC					
Overvoltage protection	Up to 36 VDC					

1/ Minimum cycle time for multi-position measurements (number of magnets ≥ 2): 400 µs

2/ With position magnet # 251 416-2

## TECHNICAL DRAWING

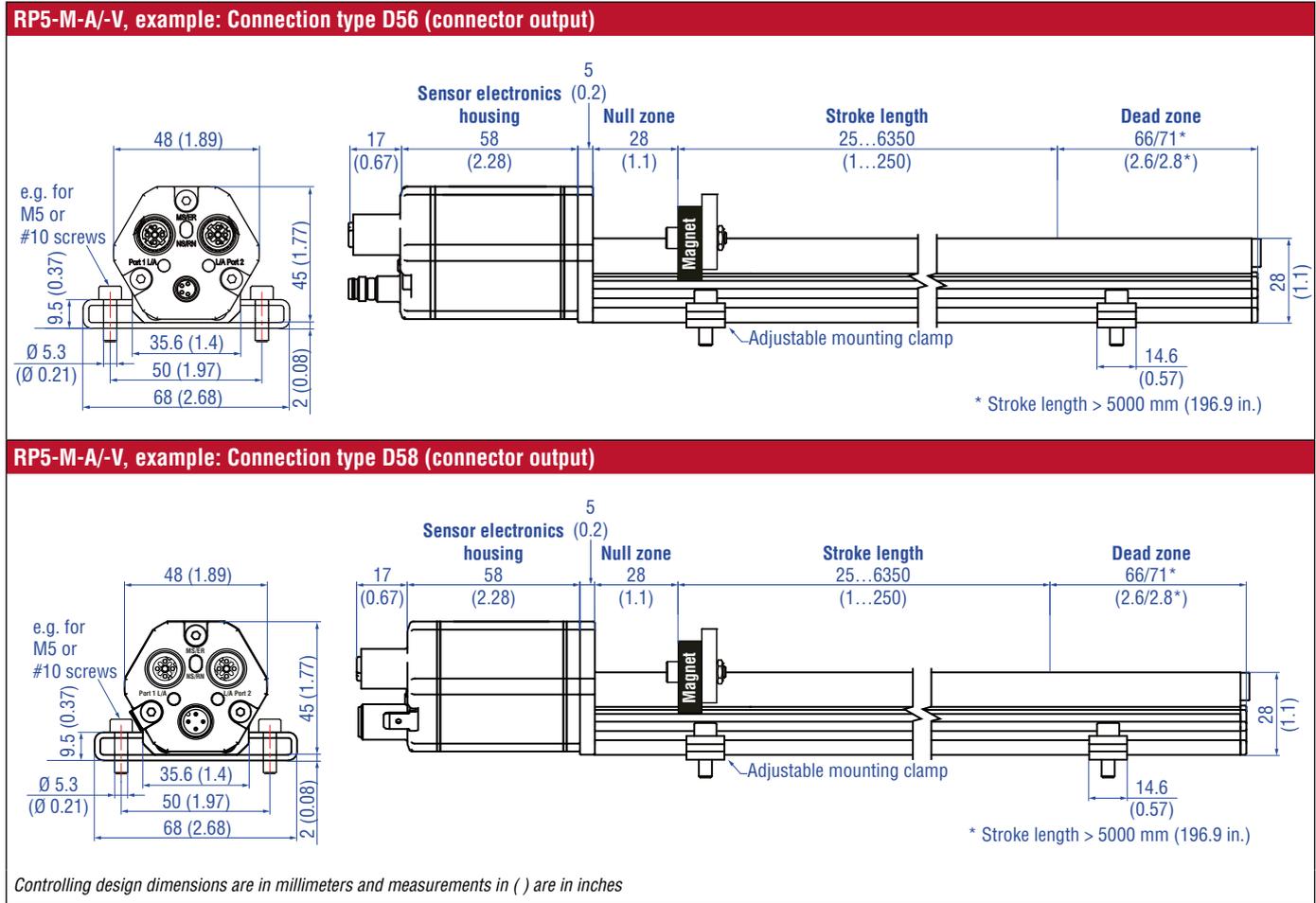


Fig. 3: Tempsonics® RP5 with U-magnet

## CONNECTOR WIRING

D56		
<b>Port 1 – Signal</b>		
<b>M12 female connector (D-coded)</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
<b>Port 2 – Signal</b>		
<b>M12 female connector (D-coded)</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
<b>Power supply</b>		
<b>M8 male connector</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	+12...30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

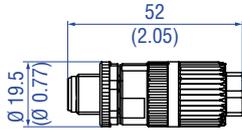
Fig. 4: Connector wiring D56

D58		
<b>Port 1 – Signal</b>		
<b>M12 female connector (D-coded)</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
<b>Port 2 – Signal</b>		
<b>M12 female connector (D-coded)</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	Tx (+)
	2	Rx (+)
	3	Tx (-)
	4	Rx (-)
<b>Power supply</b>		
<b>M12 male connector (A-coded)</b>	<b>Pin</b>	<b>Function</b>
 <p>View on sensor</p>	1	+12...30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Fig. 5: Connector wiring D58



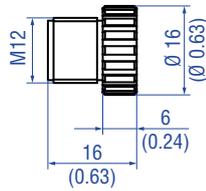
**Cable connectors\* – Signal**



**M12 D-coded male connector (4 pin), straight**  
Part no. 370 523

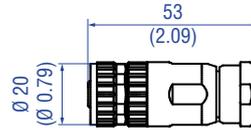
Material: Zinc nickel-plated  
Termination: Insulation-displacement  
Cable Ø: 5.5...7.2 mm (0.2...0.28 in.)  
Wire: 24 AWG – 22 AWG  
Operating temperature:  
–25...+85 °C (–13...+185 °F)  
Ingress protection: IP65 / IP67 (correctly fitted)  
Fastening torque: 0.6 Nm

**Cable connectors\* – Power**



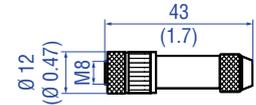
**M12 connector end cap**  
Part no. 370 537

Female connectors M12 should be covered by this protective cap  
Material: Brass nickel-plated  
Ingress protection: IP67 (correctly fitted)  
Fastening torque: 0.39...0.49 Nm



**M12 A-coded female connector (4 pin/5 pin), straight**  
Part no. 370 677

Material: GD-Zn, Ni  
Termination: Screw  
Contact insert: CuZn  
Cable Ø: 4...8 mm (0.16...0.31 in.)  
Wire: 1.5 mm<sup>2</sup>  
Operating temperature:  
–30...+85 °C (–22...+185 °F)  
Ingress protection: IP67 (correctly fitted)  
Fastening torque: 0.6 Nm



**M8 female connector (4 pin), straight**  
Part no. 370 504

Material: CuZn nickel plated  
Termination: Solder  
Cable Ø: 3.5...5 mm (0.14...0.28 in.)  
Wire: 0.25 mm<sup>2</sup>  
Operating temperature:  
–40...+85 °C (–40...+185 °F)  
Ingress protection: IP67 (correctly fitted)  
Fastening torque: 0.5 Nm

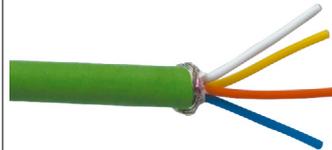
**Programming kit**

**Cables**



**TempoLink® kit for Temposonics® R-Series V**  
Part no. TL-1-0-EM08 (D56)  
Part no. TL-1-0-EM12 (D58)

- Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool
- Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m)
- User friendly interface for mobile devices and desktop computers
- See data sheet “TempoLink® smart assistant” (document part no.: [552070](#)) for further information



**PUR signal cable**  
Part no. 530 125

Material: PUR jacket; green  
Features: Cat 5, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant  
Cable Ø: 6.5 mm (0.26 in.)  
Cross section: 2 × 2 × 0.35 mm<sup>2</sup> (22 AWG)  
Operating temperature:  
–20...+60 °C (–4...+140 °F)



**Signal cable with M12 D-coded male connector (4 pin), straight – M12 D-coded, male connector (4 pin), straight**  
Part no. 530 064

Material: PUR jacket; green  
Features: Cat 5e  
Cable length: 5 m (16.4 ft)  
Cable Ø: 6.5 mm (0.26 in.)  
Ingress protection: IP65, IP67, IP68 (correctly fitted)  
Operating temperature:  
–30...+70 °C (–22...+158 °F)



**Signal cable with M12 D-coded male connector (4 pin), straight – RJ45 male connector, straight**  
Part no. 530 065

Material: PUR jacket; green  
Features: Cat 5e  
Cable length: 5 m (16.4 ft)  
Cable Ø: 6.5 mm (0.26 in.)  
Ingress protection M12 connector: IP67 (correctly fitted)  
Ingress protection RJ45 connector: IP20 (correctly fitted)  
Operating temperature:  
–30...+70 °C (–22...+158 °F)

\*/ Follow the manufacturer’s mounting instructions

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Cables



**PVC power cable**  
**Part no. 530 108**

Material: PVC jacket; gray  
Features: Shielded, flexible,  
mostly flame resistant  
Cable Ø: 4.9 mm (0.19 in.)  
Cross section: 3 × 0.34 mm<sup>2</sup>  
Bending radius: 10 × D  
Operating temperature:  
-30...+80 °C (-22...+176 °F)



**Power cable with M8 female connector**  
**(4 pin), straight – pigtail**  
**Part no. 530 066 (5 m (16.4 ft.))**  
**Part no. 530 096 (10 m (32.8 ft.))**  
**Part no. 530 093 (15 m (49.2 ft.))**

Material: PUR jacket; gray  
Features: Shielded  
Cable Ø: 5 mm (0.2 in.)  
Operating temperature:  
-40...+90 °C (-40...+194 °F)

## ORDER CODE

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
R	P	5										D	5		1	U	3		1
a			b	c	d						e	f			g	h			

<b>a</b>	<b>Sensor model</b>		
R	P	5	Profile

<b>b</b>	<b>Design</b>
G	Magnet slider backlash free (part no. 253 421), suitable for internal linearization
L	Block magnet L (part no. 403 448)
M	U-magnet OD33 (part no. 251 416-2), suitable for internal linearization
N	Magnet slider longer ball-jointed arm (part no. 252 183), suitable for internal linearization
O	No position magnet
S	Magnet slider joint at top (part no. 252 182), suitable for internal linearization
V	Magnet slider joint at front (part no. 252 184), suitable for internal linearization

<b>c</b>	<b>Mechanical options</b>
A	Standard
V	Fluorelastomer seals for the sensor electronics housing

<b>d</b>	<b>Stroke length</b>				
X	X	X	X	M	0025...6350 mm
<b>Standard stroke length (mm)</b>		<b>Ordering steps</b>			
25... 500 mm		25 mm			
500...2500 mm		50 mm			
2500...5000 mm		100 mm			
5000...6350 mm		250 mm			
X	X	X	X	U	001.0...250.0 in.
<b>Standard stroke length (in.)</b>		<b>Ordering steps</b>			
1... 20 in.		1.0 in.			
20...100 in.		2.0 in.			
100...200 in.		4.0 in.			
200...250 in.		10.0 in.			
Non-standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.					

<b>e</b>	<b>Number of magnets</b>	
X	X	01...30 position(s) (1...30 magnet(s))

<b>f</b>	<b>Connection type</b>		
D	5	6	2 × M12 female connectors (D-coded), 1 × M8 male connector
D	5	8	2 × M12 female connectors (D-coded), 1 × M12 male connector (A-coded)

<b>g</b>	<b>System</b>
1	Standard

<b>h</b>	<b>Output</b>			
U	3	0	1	POWERLINK, position and velocity (1...30 position(s))
U	3	1	1	POWERLINK, position and velocity, internal linearization (1...30 position(s))

**NOTICE**

- For RP5, the magnet selected in **b** "Design" is included in the scope of delivery. Specify the number of magnets for your application. For multi-position measurements with more than 1 magnet order the other magnets separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnet (part no. 251 416-2).
- If the option for internal linearization (U311) in **h** "Output" is chosen, select a suitable magnet.

## DELIVERY

- Sensor
  - Position magnet (not valid for RP5 with design »O«)
  - 2 mounting clamps up to 1250 mm (50 in.) stroke length  
+ 1 mounting clamp for each 500 mm (20 in.) additional stroke length
- Accessories have to be ordered separately.

Manuals, Software & 3D Models available at:  
[www.temposonics.com](http://www.temposonics.com)

**UNITED STATES**  
**Temposonics, LLC**  
Americas & APAC Region  
3001 Sheldon Drive  
Cary, N.C. 27513  
Phone: +1 919 677-0100  
E-mail: info.us@temposonics.com

**GERMANY**  
**Temposonics**  
**GmbH & Co. KG**  
EMEA Region & India  
Auf dem Schüffel 9  
58513 Lüdenscheid  
Phone: +49 2351 9587-0  
E-mail: info.de@temposonics.com

**ITALY**  
Branch Office  
Phone: +39 030 988 3819  
E-mail: info.it@temposonics.com

**FRANCE**  
Branch Office  
Phone: +33 6 14 060 728  
E-mail: info.fr@temposonics.com

**UK**  
Branch Office  
Phone: +44 79 21 83 05 86  
E-mail: info.uk@temposonics.com

**SCANDINAVIA**  
Branch Office  
Phone: +46 70 29 91 281  
E-mail: info.sca@temposonics.com

**CHINA**  
Branch Office  
Phone: +86 21 2415 1000 / 2415 1001  
E-mail: info.cn@temposonics.com

**JAPAN**  
Branch Office  
Phone: +81 3 6416 1063  
E-mail: info.jp@temposonics.com

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