Temposonics
AN AMPHENOL COMPANY

Data Sheet

R-Series V RP5 EtherNet/IP™

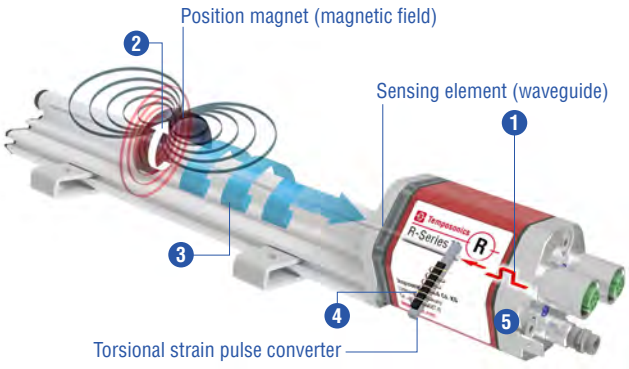
Magnetostrictive Linear Position Sensors

- EtherNet/IP™ with CIP Sync and DLR
- Position + velocity measurements for up to 20 magnets
- Field adjustments and diagnostics using the new TempoLink® smart assistant

THE NEW V GENERATION

MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.



Measurement cycle

1	Current pulse generates magnetic field
2	Interaction with position magnet field generates torsional strain pulse
3	Torsional strain pulse propagates
4	Strain pulse detected by converter
5	Time-of-flight converted into position

Fig. 1: Time-of-flight based magnetostrictive position sensing principle

R-SERIES V ETHERNET/IP™

Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. This series is the long term solution for harsh environments that have high levels of shock and vibration. The EtherNet/IP™ sensor supports CIP Sync™ (Common Industrial Protocol) and DLR (Device Level Ring) capabilities. CIP Sync™ offers synchronization between devices in an EtherNet/IP™ network, allowing for increased control coordination in time-critical applications. DLR capability provides a fault-tolerant network so that the sensor can be used in ring connection topologies when reliable continuous system operation is required. In addition, the sensors are available with internal linearization which offers improved linearity for overall higher accuracy of the position measurement values.

With many outstanding features the R-Series V sensors are fit for a very broad range of applications.

TempoLink® SMART ASSISTANT

The TempoLink® smart assistant is an accessory for the R-Series V family of sensors that supports setup and diagnostics. Depending on the sensor protocol it enables the adjustment of parameters like measurement direction, resolution and filter settings. For diagnostics and analysis of operational data the R-Series V sensors continuously track values such as total distance traveled by the positon magnet, internal temperature of the sensor and the quality of the position signal. This additional information can be read out via TempoLink® smart assistant even while the sensor remains operational in the application. TempoLink® smart assistant is connected to the sensor via the power connection, which now adds bidirectional communication for setup and diagnostics. The TempoLink® smart assistant is operated using a graphical user-interface that will be displayed on your smartphone, tablet, laptop or PC. Just connect your Wi-Fi-enabled device to TempoLink® Wi-Fi access point and go to the website URL for the user-interface.

Fig. 2: R-Series V sensor with TempoLink smart assistant

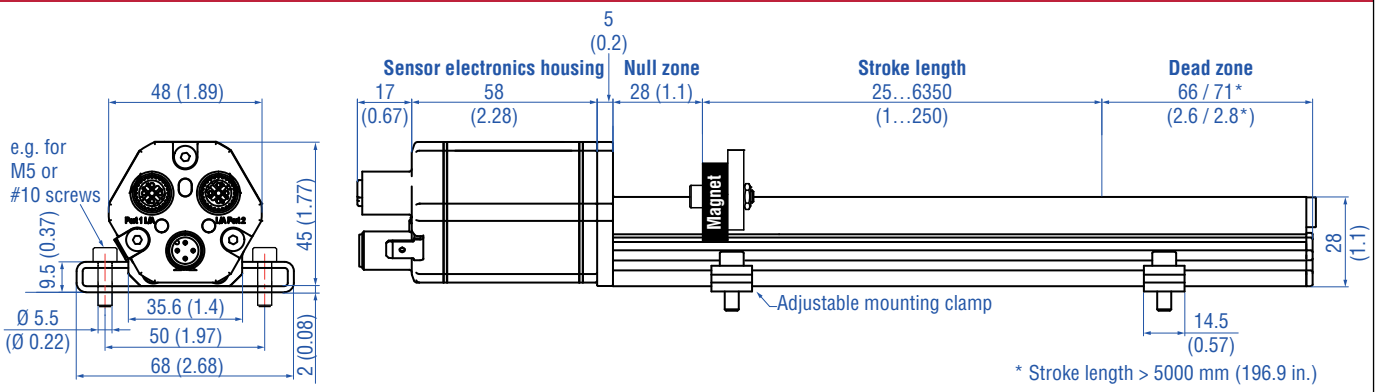
TECHNICAL DATA

Output				
Interface	EtherNet/IP™			
Data protocol	Encoder CIP device profile with CIP Sync and DLR capabilities			
Data transmission rate	100 MBit/s (maximum)			
Measured value	Position, velocity / option: Simultaneous multi-position and multi-velocity measurements up to 20 magnets			
Measurement parameters				
Resolution: Position	1…500 µm (selectable)			
Cycle time	Stroke length	≤ 2000 mm	≤ 4800 mm	≤ 6350 mm
	Cycle time	1.0 ms	2.0 ms	3.0 ms
Linearity deviation [1]	Stroke length	≤ 500 mm	> 500 mm	
	Linearity deviation	≤ ±50 µm	< 0.01 % F.S.	
Repeatability	< ±0.001 % F.S. (minimum ±2.5 µm) typical			
Hysteresis	< 4 µm typical			
Temperature coefficient	< 15 ppm / K typical			
Operating conditions				
Operating temperature	–40…+85 °C (–40…+185 °F)			
Humidity	90 % relative humidity, no condensation			
Ingress protection	IP65 (connectors correctly fitted)			
Shock test	150 g / 11 ms, IEC standard 60068-2-27			
Vibration test	30 g / 10…2000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)			
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The sensor meets the requirements of the EC directives and is marked with CE			
Magnet movement velocity	Magnet slider: Max. 10 m/s; U-magnet: Any; block magnet: Any			
Design / Material				
Sensor electronics housing	Aluminum (painted), zinc die cast			
Sensor profile	Aluminum			
Stroke length	25…6350 mm (1…250 in.)			
Mechanical mounting				
Mounting position	Any			
Mounting instruction	Please consult the technical drawings on page 4 and the operation manual (document number: 551971)			
Electrical connection				
Connection type	2 × M12 female connectors (5 pin), 1 × M8 male connector (4 pin), 2 × M12 female connectors (5 pin), 1 × M12 male connector (4 pin)			
Operating voltage	12…30 VDC ±20 % (9.6…36 VDC) [2]			
Power consumption	Less than 4 W typical			
Dielectric strength	500 VDC (DC ground to machine ground)			
Polarity protection	Up to –36 VDC			
Overvoltage protection	Up to 36 VDC			

1/ With position magnet # 252 182
2/ Power supply must be able to provide current of 1 A for power up process

TECHNICAL DRAWING

RP5-M-A/-V – RP5 with U-magnet *(connection type D58)*



Controlling design dimensions are in millimeters and measurements in ( ) are in inches

Fig. 3: Temposonics® RP5 with U-magnet

CONNECTOR WIRING

D56

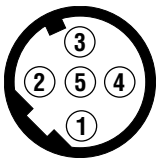
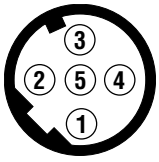
Ports		
Port 1 – M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
	5	Not connected
Port 2 – M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
	5	Not connected
Power supply		
M8 male connector	**Pin**	**Function**
 View on sensor	1	12…30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Fig. 4: Connector wiring D56

D58

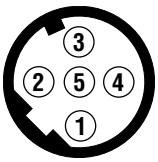
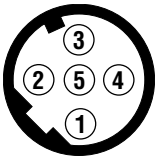
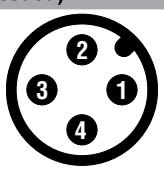
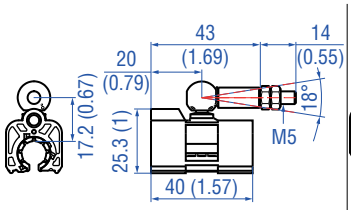
Signal		
Port 1 – M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
	5	Not connected
Port 2 – M12 female connector (D-coded)	**Pin**	**Function**
 View on sensor	1	Tx (+)
	2	Rx (+)
	3	Tx (–)
	4	Rx (–)
	5	Not connected
Power supply		
M12 male connector (A-coded)	**Pin**	**Function**
 View on sensor	1	12…30 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)
	4	Not connected

Fig. 5: Connector wiring D58

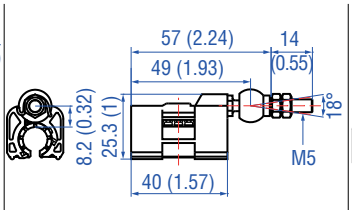
FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 551444

Position magnets



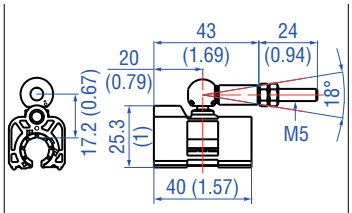
Magnet slider S, joint at top
Part no. 252 182

Material: GRP, magnet hard ferrite
Weight: Approx. 35 g
Operating temperature:
–40…+75 °C (–40…+167 °F)



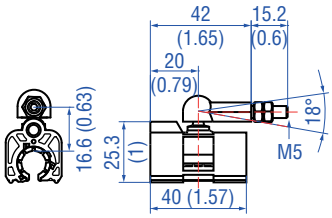
Magnet slider V, joint at front
Part no. 252 184

Material: GRP, magnet hard ferrite
Weight: Approx. 35 g
Operating temperature:
–40…+75 °C (–40…+167 °F)



Magnet slider N
longer ball-joint arm
Part no. 252 183

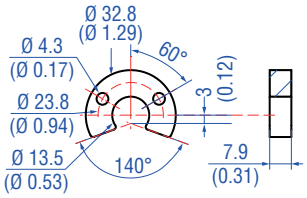
Material: GRP, magnet hard ferrite
Weight: Approx. 35 g
Operating temperature:
–40…+75 °C (–40…+167 °F)



Magnet slider G, backlash free
Part no. 253 421

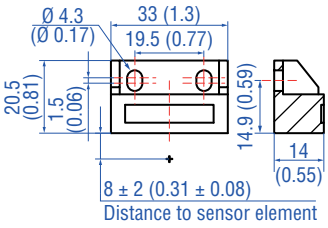
Material: GRP, magnet hard ferrite
Weight: Approx. 25 g
Operating temperature:
–40…+75 °C (–40…+167 °F)

Position magnets



U-magnet OD33
Part no. 251 416-2

Material: PA ferrite GF20
Weight: Approx. 11 g
Surface pressure: Max. 40 N/mm²
Fastening torque for M4 screws: 1 Nm
Operating temperature:
–40…+105 °C (–40…+221 °F)

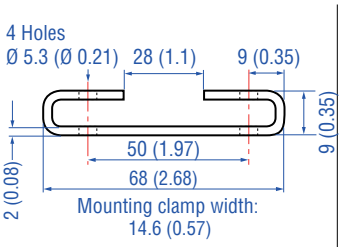


Block magnet L
Part no. 403 448

Material: Hard ferrite
Weight: Approx. 20 g
Fastening torque for M4 screws: 1 Nm
Operating temperature:
–40…+75 °C (–40…+167 °F)

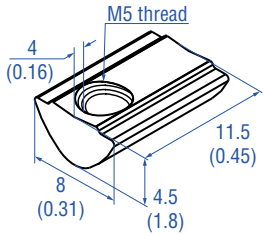
This magnet may influence the sensor performance specifications for some applications.

Mounting accessories



Mounting clamp
Part no. 400 802

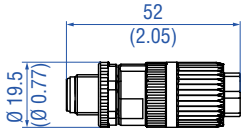
Material: Stainless steel (AISI 304)



T-nut
Part no. 401 602

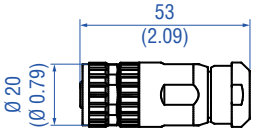
Fastening torque for M5 screw: 4.5 Nm

Cable connectors [3]



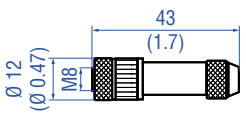
M12 D-coded male connector
(4 pin), straight
Part no. 370 523

Material: Zinc nickel-plated
Termination: Insulation-displacement
Cable Ø: 5.5…7.2 mm (0.2…0.28 in.)
Wire: 24 AWG – 22 AWG
Operating temperature:
–25…+85 °C (–13…+185 °F)
Ingress protection: IP65 / IP67
(correctly fitted)
Fastening torque: 0.6 Nm



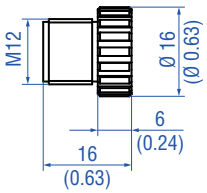
M12 A-coded female connector
(5 pin), straight
Part no. 370 677

Material: GD-Zn, Ni
Termination: Screw
Contact insert: CuZn
Cable Ø: 4…8 mm (0.16…0.31 in.)
Wire: 1.5 mm²
Operating temperature:
–30…+85 °C (–22…+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.6 Nm



M8 female connector (4 pin), straight
Part no. 370 504

Material: CuZn nickel plated
Termination: Solder
Cable Ø: 3.5…5 mm (0.14…0.28 in.)
Wire: 0.25 mm²
Operating temperature:
–40…+85 °C (–40…+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.5 Nm



M12 connector end cap
Part no. 370 537

Female connectors M12 should be covered by this protective cap
Material: Brass nickel-plated
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.39…0.49 Nm

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

3/ Follow the manufacturer's mounting instructions

Cables

PUR cable
Part no. 530 125

Material: PUR jacket; green
Features: Cat 5, highly flexible
Cable Ø: 6.5 mm (0.26 in.)
Cross section: 2 × 2 × 0.35 mm² (22/7 AWG)
Operating temperature: –20…+60 °C (–4…+140 °F)

PVC cable
Part no. 530 108

Material: PVC jacket; gray
Features: Shielded, flexible
Cable Ø: 4.9 mm (0.19 in.)
Cross section: 3 × 0.34 mm²
Operating temperature: –30…+80 °C (–22…+176 °F)

Cable with M12 D-coded male connector (4 pin), straight – M12 D-coded, male connector (4 pin), straight
Part no. 530 064

Material: PUR jacket; green
Features: Cat 5e
Cable length: 5 m (16.4 ft)
Cable Ø: 6.5 mm (0.26 in.)
Ingress protection: IP65, IP67, IP68 (correctly fitted)
Operating temperature: –30…+70 °C (–22…+158 °F)

Cable with M12 D-coded male connector (4 pin), straight – RJ45 male connector, straight
Part no. 530 065

Material: PUR jacket; green
Features: Cat 5e
Cable length: 5 m (16.4 ft)
Cable Ø: 6.5 mm (0.26 in.)
Ingress protection M12 connector: IP67 (correctly fitted)
Ingress protection RJ45 connector: IP20 (correctly fitted)
Operating temperature: –30…+70 °C (–22…+158 °F)

Cable

Cable with M8 female connector (4 pin), straight – pigtail
Part no. 530 066 (5 m (16.4 ft.))
Part no. 530 096 (10 m (32.8 ft.))
Part no. 530 093 (15 m (49.2 ft.))

Material: PUR jacket; gray
Features: Shielded
Cable Ø: 8 mm (0.3 in.)
Operating temperature: –40…+90 °C (–40…+194 °F)

Programming kit

TempoLink® kit for Temposonics® R-Series V
Part no. TL-1-0-EM08 (D56) Part no. TL-1-0-EM12 (D58)

- Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool
- Simple connectivity to the sensor via 24 VDC power line
- User friendly interface for mobile devices and desktop computers
- See product brief “TempoLink smart assistant” (document part no.: 551976) for further information

ORDER CODE

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
R	P	5										D	5		1	U	2		
a			b	c	d					e		f			g	h			

a	Sensor model	
R	P	5	Profile

b	Design
G	Magnet slider, backlash free (part no. 253 421)
L	Block magnet L (part no. 403 448)
M	U-magnet, OD33 (part no. 251 416-2)
N	Magnet slider, longer ball-jointed arm (part no. 252 183)
O	No position magnet
S	Magnet slider, joint at top (part no. 252 182)
V	Magnet slider, joint at front (part no. 252 184)

c	Mechanical options
A	Standard
V	Fluorelastomer seals for the electronics housing

d	Stroke length	
X	X	X	X	M	0025…6350 mm	
Standard stroke length (mm)*	**Ordering steps**	
25 … 500 mm	25 mm	
500…2500 mm	50 mm	
2500…5000 mm	100 mm	
5000…6350 mm	250 mm	
X	X	X	X	U	001.0…250.0 in.	
Standard stroke length (in.)*	**Ordering steps**	
1 … 20 in.	1 in.	
20…100 in.	2 in.	
100…200 in.	4 in.	
200…250 in.	10 in.	

e	Number of magnets
X	X	01…20 Position(s) (1…20 magnet(s))

f	Connection type	
D	5	6	2 × M12 female connectors (5 pin), 1 × M8 male connector (4 pin)
D	5	8	2 × M12 female connectors (5 pin), 1 × M12 male connector (4 pin)

*/ Non standard stroke lengths are available; must be encoded in 5 mm / 0.1 in. increments

g	System
1	Standard

h	Output		
U	2	0	1	EtherNet/IP™, position and velocity (1…20 positions)
U	2	1	1	EtherNet/IP™, position and velocity, internal linearization (1…20 positions)

NOTICE

- For applications using more than 1 magnet, order the additionalmagnets separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnets (part no. 251 416-2).

DELIVERY

- Sensor
- Position magnet (not valid for RP5 with design “O”)
- 2 mounting clamps up to 1250 mm (50 in.) stroke length + 1 mounting clamp for each 500 mm (20 in.) additional stroke length

Accessories have to be ordered separately.

**Manuals, Software & 3D Models available at:
www.temposonics.com**

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